DIFFERENTIAL CALCULUS ON THE SIMPLEX

C. Barceló-Vidal, J. A. Martín-Fernández

Depart. d'Informàtica i Matemàtica Aplicada Universitat de Girona - e-mail: carles.barcelo@udg.es

Summary. The purpose of this paper is to introduce the concept of differentiability of a vector-valued function on the simplex. In particular, the concepts of compositional gradient and compositional directional derivative of a real-valued function on the simplex are exposed and discussed.

1. Introduction

In some cases a response variable y is assumed to depend only on the proportions x_1, \ldots, x_D of D ingredients or parts present in a specific mixture and not on the amount of the mixture. These proportions are often expressed by volume, by weight, by mole fraction, etc. In mathematical terms the response variable y can be interpreted as a real or vector-valued function φ whose domain is a subset of the simplex space.

In many practical situations the expression $y = \varphi(x_1, ..., x_D)$ is unknown and the emphasis is on fitting the simplest model to sample or experimental data. However, in some cases, the function φ can be deduced from physical laws. One example is the rubidium-strontium method of dating Rb-minerals —based on the law of radioactivity—which uses the following function to determine the "age" t of a mineral:

$$t = \frac{1}{\lambda} \log \left[\frac{\frac{87S_T}{86S_T} - \xi_0}{\frac{87R_b}{86S_T}} + 1 \right], \tag{1}$$

where ^{86}Sr , ^{87}Sr and ^{87}Rb are, respectively, the total number of atoms of these isotopes in a unit weight of the mineral at the present time; ξ_0 is the $^{87}Sr/^{86}Sr$ ratio of strontium that was incorporated into the mineral at the time of its formation; λ is the decay constant of ^{87}Rb in units of reciprocal years ($\lambda = 1.42 \times 10^{-11} \text{ y}^{-1}$); and t is the time elapsed in years since the time of formation of mineral, that is, the "age" of the mineral. The number of ^{86}Sr atoms is constant because this isotope is stable and not produced by decay of a naturally occurring isotope of another element. The function (1) is the basis for age determination by the Rb-Sr method when the mineral has remained a "closed system" with respect to rubidium and strontium, and when the assumed value ξ_0 of the initial $^{87}Sr/^{86}Sr$ ratio is appropriate. From a mathematical point of view the expression (1) is a real-valued function defined on a subset in the simplex \mathcal{S}^3 of 3-parts ^{86}Sr - ^{87}Sr - ^{87}Rb .

In the next sections we introduce the main topics on differential calculus of the vectorvalued functions on the compositional space. We suppose known the terminology associated to the metric vector space structure of the compositional space C^d introduced in Barceló-Vidal et al. (2001) and the notation introduced in Aitchison et al. (2002).

2. Vector-valued functions on \mathcal{C}^d

2.1 Scale-invariant vector-valued functions on \mathbb{R}^D_+

Let f be a vector-valued function whose domain is a subset A in \mathbb{R}^D_+ and with range contained in \mathbb{R}^m . Thus f assigns each \mathbf{w} in A a value $f(\mathbf{w}) = (f_1(\mathbf{w}), \dots, f_m(\mathbf{w}))'$, an m-tuple in \mathbb{R}^m .

We say f is scale-invariant —or homogeneus of degree 0— if $f(k\mathbf{w}) = f(\mathbf{w})$ for every positive real k, and for every \mathbf{w} in A for which $k\mathbf{w}$ in A. Obviously, if a vector-valued function $f(\mathbf{w}) = (f_1(\mathbf{w}), \dots, f_m(\mathbf{w}))'$, with domain $A \subset \mathbb{R}_+^D$, is scale-invariant, its components f_1, \dots, f_m are also real-valued scale-invariant functions on A. And inversely, if all the components f_1, \dots, f_m are real-valued scale-invariant functions, the vector-valued function $f(\mathbf{w}) = (f_1(\mathbf{w}), \dots, f_m(\mathbf{w}))'$ is scale-invariant.

Let A be a subset of \mathbb{R}^D_+ . We define the scale closure of A, denoted A^* , as the set

$$A^* = \{k\mathbf{w} : k > 0, \mathbf{w} \in A\}.$$

The set A is said to be scale-closed, if $A^* = A$.

It is clear that any scale-invariant vector-valued function f with domain $A \subset \mathbb{R}^D_+$ can be extended to the scale closure A^* of A. It suffices to define $f(k\mathbf{w}) = f(\mathbf{w})$ (k > 0) ($\mathbf{w} \in A$). Obviously, this extended function with domain A^* is also scale-invariant. Therefore, throughout this paper, we shall implicitly suppose that the domain of any scale-invariant function is always an scale-closed subset.

Let $f:A \longrightarrow \mathbb{R}^m$ be an scale-invariant vector-valued function defined on a subset A in \mathbb{R}^D_+ with values in \mathbb{R}^m . It induces a vector-valued function $\underline{f}:A \longrightarrow \mathbb{R}^m$ defined on $A = \operatorname{ccl} A$ in C^d . Certainly, if \mathbf{c} is a composition which belongs to A, there exists at least a vector \mathbf{w} in A such that $\operatorname{ccl} \mathbf{w} = \mathbf{c}$. Then, we define $\underline{f}(\mathbf{c})$ as equal to $f(\mathbf{w})$. As f is scale-invariant, it is clear that $\underline{f}(\mathbf{c})$ is univocally defined. We will denote by \underline{f} the vector-valued function defined on $A = \operatorname{ccl} A$ in C^d associated to the scalar invariant vector-function f defined on the scalar-closed subset f in f

2.2 C-linear functions on C^d

According to the vector space structure of $(\mathcal{C}^d, \oplus, \otimes)$, a vector-valued function $\varphi : \mathcal{C}^d \longrightarrow \mathbb{R}^m$ is \mathcal{C} -linear if

$$\varphi(\underline{\mathbf{w}} \oplus \underline{\mathbf{w}}^*) = \varphi(\underline{\mathbf{w}}) + \varphi(\underline{\mathbf{w}}^*) \quad (\underline{\mathbf{w}}, \underline{\mathbf{w}}^* \in \mathcal{C}^d),$$

and

$$\varphi(\lambda \otimes \underline{\mathbf{w}}) = \lambda \varphi(\underline{\mathbf{w}}) \quad (\underline{\mathbf{w}} \in \mathcal{C}^d) \ (\lambda \in \mathbb{R}).$$

It can be proved that, φ is \mathcal{C} -linear if and only if there exists a constant $m \times D$ matrix \mathbf{A} , constrained by the equality $\mathbf{A}\mathbf{1}_D = \mathbf{0}_m$, such that $\underline{f} = \varphi$, where $f: \mathbb{R}_+^D \longrightarrow \mathbb{R}^m$ is

the real-valued function defined by the expression

$$f(\mathbf{w}) = \mathbf{A} \log \mathbf{w} \quad (\mathbf{w} \in \mathbb{R}^D_+).$$

3. Derivatives on \mathcal{C}^d

3.1 Derivative of scale-invariant vector-valued functions on \mathbb{R}^D_+

Let $f = (f_1, ..., f_m) : A \longrightarrow \mathbb{R}^m$ be a vector-valued function whose domain is an open subset A in \mathbb{R}^D_+ . If f is differentiable at $\mathbf{w}^* \in A$, we will denote by

$$\mathbf{D}f(\mathbf{w}^*) = \begin{bmatrix} \frac{\partial f_1}{\partial w_1}(\mathbf{w}^*) & \dots & \frac{\partial f_1}{\partial w_D}(\mathbf{w}^*) \\ \vdots & \dots & \vdots \\ \frac{\partial f_m}{\partial w_1}(\mathbf{w}^*) & \dots & \frac{\partial f_m}{\partial w_D}(\mathbf{w}^*) \end{bmatrix}$$

the derivative of f at \mathbf{w}^* . Therefore, this derivative is a $m \times D$ matrix referred to as the matrix of partial derivatives of f at \mathbf{w}^* . In particular, if f is a real-valued function, its derivative at \mathbf{w}^*

$$\mathbf{D}f(\mathbf{w}^*) = \begin{bmatrix} \frac{\partial f}{\partial w_1}(\mathbf{w}^*) & \dots & \frac{\partial f}{\partial w_D}(\mathbf{w}^*) \end{bmatrix}$$

is called the gradient of f at \mathbf{w}^* and denoted by $\nabla f(\mathbf{w}^*)$.

According to the well-known Euler's theorem for homogeneous functions, if f is scale-invariant and differentiable at $\mathbf{w}^* \in A$, then

$$\sum_{i=1}^{D} w_j^* \frac{\partial f_i}{\partial w_j}(\mathbf{w}^*) = 0$$

for each i = 1, ..., m. Furthermore, f is also differentiable at $k\mathbf{w}^*$, for each k > 0, and

$$\frac{\partial f_i}{\partial w_j}(k\mathbf{w}^*) = \frac{1}{k} \frac{\partial f_i}{\partial w_j}(\mathbf{w}^*)$$

for each $i = 1, \ldots, m$, and $j = 1, \ldots, D$.

3.2 Derivative of vector-valued functions on C^d

Let $f = (f_1, \ldots, f_m) : A \longrightarrow \mathbb{R}^m$ be a scale-invariant vector-valued function whose domain is an open and scale-closed subset A in \mathbb{R}^D_+ . Let $\underline{f} = (\underline{f_1}, \ldots, \underline{f_m})$ be the vector-valued function defined on $A = \operatorname{ccl} A$ in C^d associated to function f.

We say that \underline{f} is C-differentiable at $\underline{\mathbf{w}}^*$ in \mathcal{A} if it exists a $m \times D$ matrix \mathbf{A} , constrained by the equality $\mathbf{A}\mathbf{1}_D = \mathbf{0}_m$, such that

$$\lim_{\underline{\mathbf{u}} \to \mathbf{1}_{D}} \frac{\parallel \underline{f}(\underline{\mathbf{w}}^{*} \oplus \underline{\mathbf{u}}) - \underline{f}(\underline{\mathbf{w}}^{*}) - \mathbf{A} \log \underline{\mathbf{u}} \parallel}{\parallel \underline{\mathbf{u}} \parallel_{\mathcal{C}}} = 0,$$

where $\underline{\mathbf{1}_D} = \operatorname{ccl}(1, \dots, 1)'$ is the neutral element of (\mathcal{C}^d, \oplus) .

The element (i, j)-th of matrix \mathbf{A} will referred to as the \mathcal{C} -partial derivative of $\underline{f_i}$ with respect to the j-th coordinate at $\underline{\mathbf{w}}^*$ and is denoted by $\frac{\partial_{\mathcal{C}} f_i}{\partial w_i}(\underline{\mathbf{w}}^*)$. It is easy to prove that

$$\frac{\partial_{\mathcal{C}}\underline{f_i}}{\partial w_i}(\underline{\mathbf{w}^*}) = \lim_{t \to 0} \frac{f_i(w_1^*, \dots, w_{j-1}^*, w_j^* \exp t, w_{j+1}^*, \dots, w_D^*) - f_i(\underline{\mathbf{w}^*})}{t}.$$

From this interpretation of the C-partial derivatives, it is not difficult to prove that \underline{f} is C-differentiable at $\underline{\mathbf{w}}^*$ in A if and only if f is differentiable at \mathbf{w}^* in A. Furthermore, the C-partial derivatives of \underline{f} at $\underline{\mathbf{w}}^*$ and the partial derivatives of f at \mathbf{w}^* are related by the equality

$$\frac{\partial_{\mathcal{C}} \underline{f_i}}{\partial w_i} (\underline{\mathbf{w}}^*) = w_j^* \frac{\partial f_i}{\partial w_i} (\mathbf{w}^*),$$

for each $i = 1, \ldots, m$, and $j = 1, \ldots, D$.

The matrix

$$\mathbf{A} = \begin{bmatrix} \frac{\partial_{\mathcal{C}} f_{1}}{\partial w_{1}} (\mathbf{\underline{w}^{*}}) & \dots & \frac{\partial_{\mathcal{C}} f_{1}}{\partial w_{D}} (\mathbf{\underline{w}^{*}}) \\ \vdots & \dots & \vdots \\ \frac{\partial_{\mathcal{C}} f_{m}}{\partial w_{1}} (\mathbf{\underline{w}^{*}}) & \dots & \frac{\partial_{\mathcal{C}} f_{m}}{\partial w_{D}} (\mathbf{\underline{w}^{*}}) \end{bmatrix}$$

will be referred to as the matrix of C-partial derivatives of \underline{f} at $\underline{\mathbf{w}}^*$ and will be denoted by $\mathbf{D}_{\mathcal{C}}f(\underline{\mathbf{w}}^*)$.

In particular, if \underline{f} is a real-valued function, the matrix of C-partial derivatives of \underline{f} at $\underline{\mathbf{w}}^*$

$$\mathbf{D}_{\mathcal{C}}\underline{f}(\underline{\mathbf{w}^*}) = \left[\frac{\partial_{\mathcal{C}}\underline{f}}{\partial w_1}(\underline{\mathbf{w}^*}), \dots, \frac{\partial_{\mathcal{C}}\underline{f}}{\partial w_D}(\underline{\mathbf{w}^*})\right]$$

is called the C-gradient of \underline{f} at $\underline{\mathbf{w}}^*$ and denoted by $\nabla_{\mathcal{C}}\underline{f}(\underline{\mathbf{w}}^*)$. The first-order Taylor approximation of f in a neighbourhood of $\underline{\mathbf{w}}^*$ is given by

$$\underline{f}(\underline{\mathbf{w}^*};\underline{\mathbf{u}}) = \underline{f}(\underline{\mathbf{w}^*}) + \sum_{j=1}^{D} \left(\frac{\partial_{\mathcal{C}} \underline{f}}{\partial w_j} (\underline{\mathbf{w}^*}) \right) \log u_j + R_1(\underline{\mathbf{w}^*};\underline{\mathbf{u}}),$$

where $\underline{\mathbf{u}} = \operatorname{ccl}(u_1, \dots, u_D)'$, and $R_1(\underline{\mathbf{w}}^*; \underline{\mathbf{u}}) / \parallel \underline{\mathbf{u}} \parallel_{\mathcal{C}} \to 0$ in \mathbb{R} as $\underline{\mathbf{u}} \stackrel{\mathcal{C}}{\to} \underline{\mathbf{1}}_D$ in \mathcal{C}^d .

4. Directional derivatives on C^d

Let $f: \mathbb{R}^D_+ \to \mathbb{R}$ be a scale-invariant real-valued function defined on \mathbb{R}^D_+ and \underline{f} be the real-valued function defined on \mathcal{C}^d associated to function f. Let $\underline{\mathbf{w}^*}, \underline{\mathbf{u}} \in \mathcal{C}^d$.

Then, the *C*-directional derivative of \underline{f} at $\underline{\mathbf{w}}^*$ along the direction $\underline{\mathbf{u}}$ is given by

$$\left(\frac{d\underline{f}(\underline{\mathbf{w}}^* \oplus (t \otimes \underline{\mathbf{u}}))}{dt}\right)_{t=0}$$

if this exists. From this definition, it is no difficult to prove that the C-directional derivative can also be defined by the formula

$$\lim_{t\to 0} \frac{f(w_1^* u_1^t, \dots, w_D^* u_D^t) - f(w_1^*, \dots, w_D^*)}{t}$$

If f is differentiable, then all C-directional derivatives of \underline{f} exist. Furthermore, the C-directional derivative at $\underline{\mathbf{w}}^* \in C^d$ along the direction $\underline{\mathbf{u}} \in C^{\overline{d}}$ is given by

$$\sum_{j=1}^{D} w_j^* \frac{\partial f}{\partial w_j}(\mathbf{w}^*) \log u_j = \nabla_{\mathcal{C}} \underline{f}(\underline{\mathbf{w}}^*) \log \mathbf{u}. \tag{2}$$

Therefore, if $\nabla_{\mathcal{C}}\underline{f}(\underline{\mathbf{w}^*}) \neq \mathbf{0}'_D$, the composition $\operatorname{ccl}\left\{\exp\left(\nabla_{\mathcal{C}}\underline{f}(\underline{\mathbf{w}^*})'\right)\right\}$ points in the direction along which f is increasing the fastest in a \mathcal{C} -neighbourhood of $\underline{\mathbf{w}^*}$.

We can deduce from (2) that the C-directional derivative of \underline{f} at $\underline{\mathbf{w}}^* \in C^d$ along the direction

$$\underline{\mathbf{u}_j} = \operatorname{ccl}(\underbrace{1, \dots, 1}_{j-1}, e, \underbrace{1, \dots, 1}_{D-j})' \quad (j = 1, \dots, D)$$

is equal to

$$\frac{\partial_{\mathcal{C}} f}{\partial w_j}(\underline{\mathbf{w}}^*) = w_j^* \frac{\partial f}{\partial w_j}(\underline{\mathbf{w}}^*). \tag{3}$$

If the C-directional derivative of \underline{f} along the direction $\underline{\mathbf{u}}_j$ is equal to 0 on C^d , we say that \underline{f} is C-independent of the j-th part. It is clear from $\overline{(3)}$ that \underline{f} is C-independent of the j-th part if and only if f does not depend of the j-th coordinate w_j on \mathbb{R}^D_+ .

5. Example

The function (1) giving the "age" t of a mineral from the ${}^{87}Sr/{}^{86}Sr$ and ${}^{87}Rb/{}^{86}Sr$ ratios can be interpreted as a scale-invariant real-valued function f

$$\left({}^{86}Sr, {}^{87}Sr, {}^{87}Rb\right) \xrightarrow{f} \frac{1}{\lambda} \log \left[\frac{{}^{87}Sr}{{}^{86}Sr} - \xi_0}{{}^{87}Rb} + 1\right]$$

defined on

$$A = \left\{ \left({}^{86}Sr, {}^{87}Sr, {}^{87}Rb \right)' \in \mathbb{R}^3_+ : \frac{{}^{87}Sr}{{}^{86}Sr} - \xi_0 \ge 0 \right\}.$$

Therefore, the function f induces a real-valued function \underline{f} defined on $\mathcal{A} = \operatorname{ccl} A$ in \mathcal{C}^2 . This function \underline{f} can also be interpreted as a function on the simplex \mathcal{S}^3 . Figure 1 shows some level contours of this function for $\lambda = 1.42 \times 10^{-11}$ and $\xi_0 = 0.7071$. The projections of these level contours on the simplex are straight segments from a common point on the $^{86}Sr - ^{87}Sr$ edge.

The C-gradient of \underline{f} at $\underline{\mathbf{w}} = \operatorname{ccl} \left({^{86}Sr,^{87}Sr,^{87}Rb} \right)'$ is equal to

$$\nabla_{\mathcal{C}}\underline{f}(\underline{\mathbf{w}}) = \frac{1/\lambda}{\left(\frac{87S_T}{86S_T} - \xi_0\right) + \frac{87R_b}{86S_T}} \left[-\xi_0, \frac{87S_T}{86S_T}, -\left(\frac{87S_T}{86S_T} - \xi_0\right) \right] \tag{4}$$

From (4) we deduce that $\frac{\partial_c \underline{f}}{\partial^{87}Sr}(\underline{\mathbf{w}})$ is always positive in each $\underline{\mathbf{w}} \in \mathcal{A}$. It means that the "age" of a mineral increases when ${}^{87}Sr$ increases and the ${}^{87}Rb/{}^{86}Sr$ ratio remains constant. Similarly, the \mathcal{C} -partial derivative $\frac{\partial_c \underline{f}}{\partial^{87}Rb}(\underline{\mathbf{w}})$ is negative in each $\underline{\mathbf{w}}$ in the \mathcal{C} -interior of \mathcal{A} . Therefore, the "age" of a mineral decreases when ${}^{87}Rb$ increases and the ${}^{87}Sr/{}^{86}Sr$ ratio remains constant.

Any of the three dotted paths in Figure (1) represents in each point the direction in which the values of function \underline{f} change most rapidly, showing the evolution of the (${}^{86}Sr$ - ${}^{87}Sr$ - ${}^{87}Rb$)-composition of a mineral from the time of its formation.

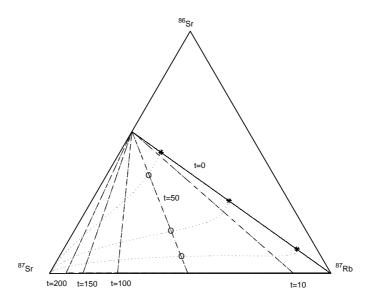


Figure 1: Level contours $(t = 0; 10 \times 10^9; 50 \times 10^9; 100 \times 10^9; 150 \times 10^9; 200 \times 10^9 \text{ years})$ of the function $t = \frac{1}{1.42 \times 10^{-11}} \log \left[\frac{\frac{87_{S_r}}{86_{S_r}} - 0.7071}{\frac{87_{CB}}{86_{S_r}}} + 1 \right]$ on the simplex of 3-parts $^{86}Sr^{-87}Sr^{-87}Rb$. The dotted lines show the evolution of the $(^{86}Sr^{-87}Sr^{-87}Rb)$ -composition of three minerals from the time of their formation

References

Aitchison, J., C. Barceló-Vidal, J. J. Egozcue, and V. Pawlowsky-Glahn (2002). A concise guide to the algebraic-geometric structure of the simplex, the sample space for compositional data analysis. In *Proceedings of IAMG'02*, Berlin.

Barceló-Vidal, C., J. A. Martín-Fernández, and V. Pawlowsky-Glahn (2001). Mathematical foundations of compositional data analysis. In G. Ross (Ed.), *Proceedings of IAMG'01* — The sixth annual conference of the International Association for Mathematical Geology, Volume CD, pp. 20 p. electronic publication.